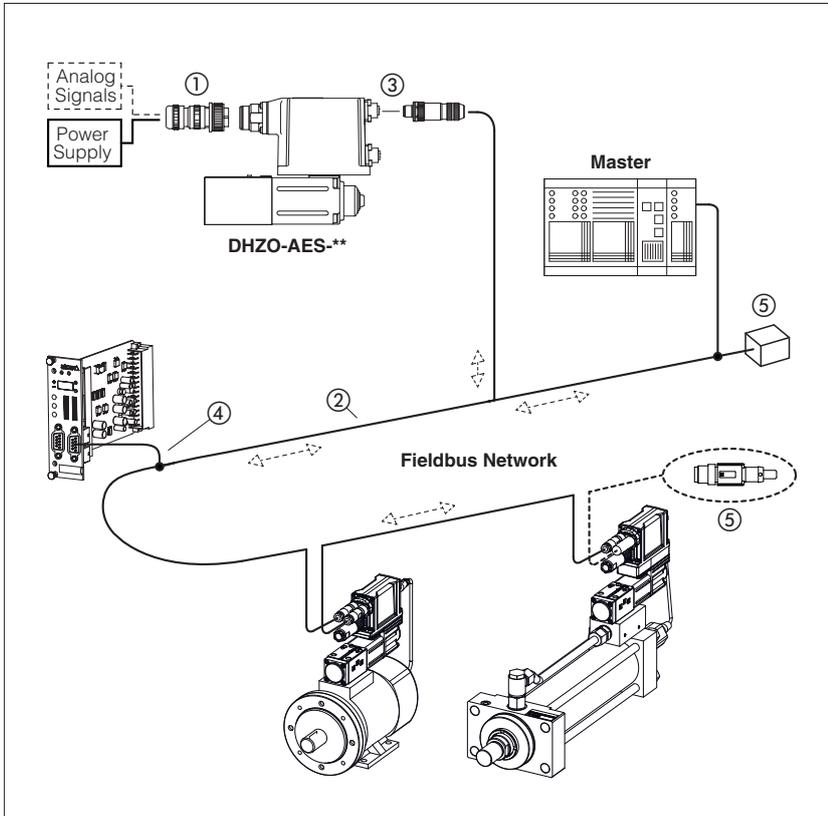


# Fieldbus

BC (CANopen), BP (PROFIBUS DP), EH (EtherCAT), EW (POWERLINK), EI (EtherNet/IP)

Typical CANopen or PROFIBUS DP fieldbus network



Fieldbus communication interfaces are available for digital proportional drivers and controllers, granting several plus:

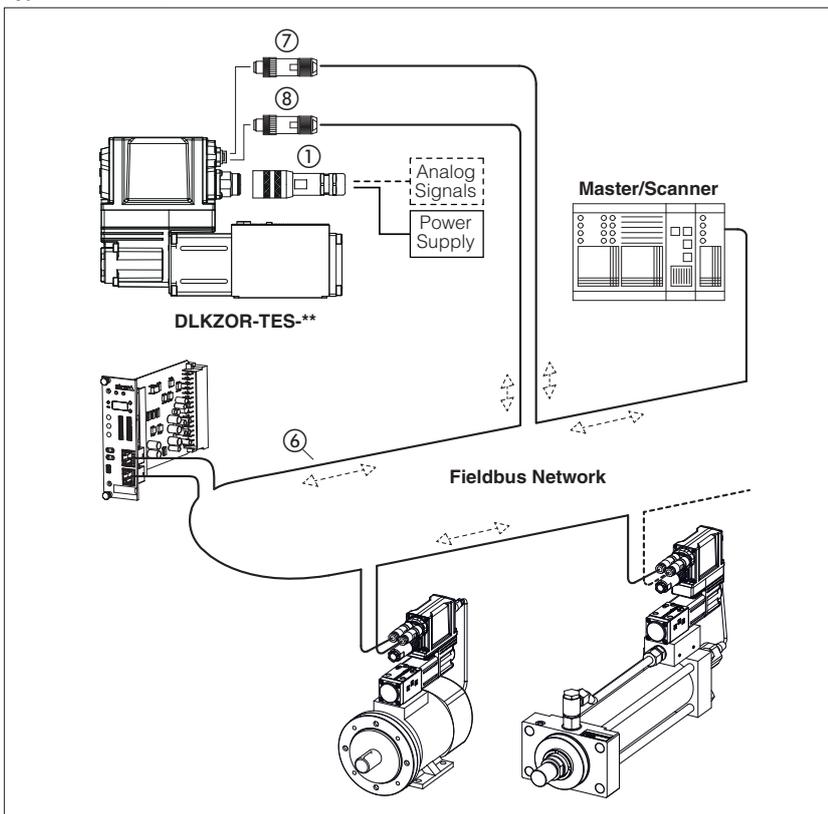
- more information available for machine operation to enhance its performances
- improved accuracy and robustness of digital transmitted information
- costs reduction due to simpler and standardized wiring solutions
- costs reduction due to fast and simple installation and maintenance
- direct integration into machine's communication networks

These executions allow to operate proportional valves and pumps through fieldbus or using the analog signals on main connector ①.

### Fieldbus distributed-control

Fieldbus communication allows to share all the available information of the digital drivers and controllers (reference, monitor, etc). This distributed-control design allows to implement powerful machines functionalities for tuning, diagnostic, maintenance, etc.

Typical EtherCAT, POWERLINK or EtherNet/IP fieldbus network



### CANopen and PROFIBUS DP

CANopen and PROFIBUS DP networks consist of a common cable (2 twisted wire, ②) for digital communication: several devices (node ③) can be connected to this main cable by means of short cable branches ④. The two endpoints of the main cable must be terminated with specific devices (terminator, ⑤) to dissipate or absorb the communication signal's energy thus preventing interferences and degradations of fieldbus transmission.

### EtherCAT, POWERLINK, EtherNet/IP

EtherCAT, POWERLINK and EtherNet/IP networks consist in a Ethernet common cable (4 twisted wire, ⑥) for digital communication. All EtherCAT, POWERLINK and EtherNet/IP slave/adaptor devices have always the double connector for signal input ⑦ and signal output ⑧.

The main Ethernet cable starting from the EtherCAT, POWERLINK or EtherNet/IP master/scanner, has to be connected to the slave/adaptor input connector.

The slave/adaptor output connector has to be connected to the next slave/adaptor input connector.

## 1 CANopen features for digital drivers and controllers in BC execution

### Physical

|                     |  |
|---------------------|--|
| Serial input format | Industrial field-bus with optical insulation type CAN-Bus ISO11898 |
| Transmission rate   | Transmission rates from 10 Kbit/s to 1 Mbit/s                      |
| Max node            | 32 per segment without repeater; 127 per segment with repeater     |

### Communication Protocol

|                 |   |
|-----------------|---|
| Data Link Layer | DS301 V4.2.0 - based on CAN standard frame with 11-bit identifier |
| Device Profile  | DS408 - Fluid Power Technology (EN50325-4)                        |
| Device type     | Slave   |

### Startup and configuration (as per DS301+DSP305)

|                  |   |
|------------------|---|
| Boot up process  | Minimum boot-up   |
| Node setting     | LSS (Layer Setting Services)<br>SDO<br>E-SW-FIELDBUS and Z-SW-FULL programming software<br>dip-switches (only for TERS ex-proof, AERS ex-proof) |
| Baudrate setting | LSS (Layer Setting Services), SDO   |
| Baudrate         | 10 / 20 / 50 (default) / 125 / 250 / 500 / 1000Kbit/s   |

### Fieldbus communication diagnostic (as per DS301)

|               |                            |
|---------------|----------------------------|
| Device Error  | Emergency                  |
| Network Error | Node Guarding<br>Heartbeat |

### Real-time communication (as per DS301 + DS408)

|               |   |
|---------------|---|
| RPDO          | Four mappable PDOs to the drivers:<br>AES, BM-AES, TES, LES, RES, BM-RES, PES, TERS ex-proof, AERS ex-proof<br>Four mappable PDOs to the controllers:<br>TEZ, LEZ     |
| TPDO          | Four mappable PDOs from the drivers:<br>AES, BM-AES, TES, LES, RES, BM-RES, PES, TERS ex-proof, AERS ex-proof<br>Four mappable PDOs from the controllers:<br>TEZ, LEZ |
| R(T)PDO types | Event Triggered, Remotely requested, Sync(cyclic) and Sync(acyclic)   |

### Non real-time communication (as per DS301 + DS408)

|     |                               |
|-----|-------------------------------|
| SDO | One SDO (1 Server + 1 Client) |
|-----|-------------------------------|

### Standard references

#### ISO 11898

Road Vehicles – Interchange of digital information controller area network (CAN) for High-speed communication

#### EN50325-4

Industrial communication subsystem based on ISO 11898 (CAN) for controller device interfaces

#### CiA DS301

CANopen – Application Layer and Communication Profile for Industrial Systems

#### CiA DR303-1

Cabling and connector pin assignment

#### CiA DSP305

CANopen – Layer Setting Services and Protocol

#### CiA DS408

CANopen – Device Profile for Proportional Hydraulic Valves v 1.5.2

### Programming interface

E-SW-FIELDBUS and Z-SW-FULL software using proper cable/adaptor (see tech table **GS500**) or CANopen master device

### Configuration file

EDS (Electronic Data Sheet), enclosed in programming software DVD E-SW-FIELDBUS and Z-SW-FULL

### Manuals

E-MAN-S-BC and STARTUP-FIELDBUS, enclosed in programming software DVD E-SW-FIELDBUS

Z-MAN-S-BC and STARTUP-FULL, enclosed in programming software DVD Z-SW-FULL

## 2 PROFIBUS DP features for digital drivers and controllers in BP execution

### Physical

|                     |  |
|---------------------|--|
| Serial input format | Industrial field-bus with optical insulation type PROFIBUS-DP RS485<br>European fieldbus standard (lev.1 – EN50170-part 2) |
| Transmission rate   | Transmission rates from 9,6 Kbit/s to 12 Mbit/s  |
| Max node            | 32 per segment without repeater; 126 node with repeater  |

### Communication Protocol

|                 |  |
|-----------------|--|
| Data Link Layer | PROFIBUS DPV0 - IEC 61158 (type 3)             |
| Device Profile  | PROFIBUS-DP Profile for Fluid Power Technology |
| Device type     | Slave  |

### Startup and configuration

|                  |  |
|------------------|--|
| Boot up process  | SAP 61 for sending parameter setting data<br>SAP 62 for checking configuration data                                    |
| Node setting     | SAP 55<br>E-SW-FIELDBUS and Z-SW-FULL programming software<br>dip-switches (only for TERS ex-proof, AERS ex-proof, KZ) |
| Baudrate setting | Automatic  |
| Baudrate         | 9,6 / 19,2 / 45,45 / 93,75 / 187,5 / 500 / 1500 / 3000 / 6000 / 12000 Kbit/s   |

### Fieldbus communication diagnostic

|              |        |
|--------------|--------|
| Device error | SAP 60 |
|--------------|--------|

### Real-time communication

|     |  |
|-----|--|
| PZD | Process data area of PPO telegram by Data Exchange, default SAP:<br>cyclic transmission of standard Profibus frame |
|-----|--|

#### Standard electronics - drivers

##### *PPO type 3 for:*

AES s40, BM-AES s10, TES s40, LES s40, RES s10, BM-RES s10

##### *PPO type 5 for:*

TES s40, LES s40, PES s40 with S option

##### *PPO type 113, 213, 230 for:*

TES s40, LES s40, RES s10

##### *PPO type 115, 214, 240 for:*

TES s40, LES s40, PES s40 with S option

#### Standard electronics - controllers

##### *PPO type 1, 101, 103 for:*

TEZ s40, LEZ s40, KZ s11

##### *PPO type 111, 121, 123, 223, 227 for:*

TEZ s40, LEZ s40

#### Ex-proof electronics - drivers

##### *PPO type 3 for:*

AES s30, TES s31, LES s31, TERS s31, AERS s31

##### *PPO type 5 for:*

TES s31, LES s31

|             |                           |
|-------------|---------------------------|
| Cyclic mode | standard, sync and freeze |
|-------------|---------------------------|

### Non real-time communication

|     |   |
|-----|---|
| PKW | Parameter data area of PPO telegram by Data Exchange, default SAP:<br>acyclic transmission of standard Profibus frame |
|-----|---|

### Standard references

#### *PROFIBUS profile*

PROFIBUS Profile,  
Fluid Power Technology,  
Edition Oct. 2001

#### *VDMA profile*

Fluid Power Technology,  
Proportional Valves and  
Hydrostatic Transmissions, ver 1.1

### Programming interface

E-SW-FIELDBUS and Z-SW-FULL software using proper cable/adaptor (see tech table **GS500**) or PROFIBUS DP master device

### Configuration file

GSD (General Station Description) enclosed in programming software DVD E-SW-FIELDBUS and Z-SW-FULL

### Manuals

E-MAN-S-BP and STARTUP-FIELDBUS, enclosed in programming software DVD E-SW-FIELDBUS

Z-MAN-S-BP and STARTUP-FULL, enclosed in programming software DVD Z-SW-FULL

### 3 EtherCAT features for digital drivers and controllers in EH execution

#### Physical

|                     |   |
|---------------------|---|
| Serial input format | Industrial fieldbus type Fast Ethernet galvanically insulated IEC 61158-2 |
| Transmission rate   | 2 x 100 Mbit/s (Fast Ethernet, Full-Duplex)                               |
| Max node            | 65535 slaves  |
| Ethernet Standard   | ISO/IEC 8802-3 frame format   |
| EtherType           | 0x88A4 according IEEE 802.3   |
| Cable length        | 0,2 - 100m (between two slave devices)                                    |
| Cable type          | CAT5 (4 wire twisted pair) according with T568B                           |
| Network topology    | Line, tree and star   |
| Termination         | Device internally   |

#### Communication Protocol

|                    |  |
|--------------------|--|
| Data Link Layer    | EtherCAT use Standard Ethernet Frames:<br>ISO/IEC 8802-3 + IEC 61784-2           |
| Device Profile     | CANopen over EtherCAT (CoE) DS408 - Fluid Power Technology<br>EN 50325-4         |
| Device type        | Slave  |
| Supported protocol | CANopen SDO Mailbox-Interface "CoE"<br>Network Management<br>PDO<br>PDO Watchdog |

#### Startup and configuration (as per DS301+DSP305)

|              |   |
|--------------|---|
| Node setting | Automatic position addressing<br>Device node addressing |
| Baudrate     | 100 Mbit/s (Automatic)                                  |

#### Fieldbus communication diagnostic (as per DS301)

|              |           |
|--------------|-----------|
| Device Error | Emergency |
|--------------|-----------|

#### Real-time communication (as per DS301 + DS408)

|               |  |
|---------------|--|
| RPDO          | 4 PDOs messages to the driver (up to 32 byte for each PDO)   |
| TPDO          | 4 PDOs messages from the driver (up to 32 byte for each PDO) |
| R(T)PDO types | Remotely requested   |

#### Non real-time communication (as per DS301 + DS408)

|     |                               |
|-----|-------------------------------|
| SDO | One SDO (1 Server + 1 Client) |
|-----|-------------------------------|

#### Standard references

##### ISO 11898

Road Vehicles – Interchange of digital information controller area network (CAN) for High-speed communication

##### EN 50325-4

Industrial communication subsystem based on ISO 11898 (CAN) for controller device interfaces

##### CiA DS301

CANopen – Application Layer and Communication Profile for Industrial Systems

##### CiA DSP305

CANopen – Layer Setting Services and Protocol

##### CiA DS408

CANopen – Device Profile for Proportional Hydraulic Valves v 1.5.1

##### IEC 61076-2-101

Connectors for electronic equipment  
- Product Requirements -  
Part 2-101: Circular connectors  
- Detail specification for M12 connectors with screw-locking

##### IEC 61158-2

Industrial communication networks  
- Fieldbus specification -  
Part 2: Physical layer specification and service definition

##### IEC 61784-2

Industrial communication networks  
- Profiles -  
Part 2: Additional fieldbus profiles for real-time networks based on ISO/IEC 8802-3

#### Programming interface

E-SW-FIELDBUS and Z-SW-FULL software using proper cable/adaptor (see tech table **GS500**) or EtherCAT master device

#### Configuration file

XML (Extensible Markup Language) enclosed in programming software DVD E-SW-FIELDBUS and Z-SW-FULL

#### Manuals

E-MAN-S-EH and STARTUP-FIELDBUS, enclosed in programming software DVD E-SW-FIELDBUS  
Z-MAN-S-EH and STARTUP-FULL, enclosed in programming software DVD Z-SW-FULL

**4 POWERLINK features for digital drivers and controllers in EW execution**

|  |  |
|--|--|
| <b>Physical</b>  |  |
| Serial input format  | Industrial fieldbus type Fast Ethernet galvanically insulated IEC 61158-2  |
| Transmission rate  | 2 x 100 Mbit/s (Fast Ethernet, Half-Duplex)  |
| Max node   | 239 slaves   |
| Ethernet Standard  | ISO/IEC 8802-3 frame format  |
| EtherType  | 0x88AB according IEEE 802.3  |
| Integrated Hub   |  |
| Cable length   | 0,2 - 100m (between two slave devices)   |
| Cable type   | CAT5 (4 wire twisted pair) according with T568B  |
| Network topology   | Line, tree, star, daisy chain, ring structure or any combination of these topologies   |
| Ethernet Hub   | Integrated with 2 ports:<br>- one led for Link/Activity indicator (on each port)<br>- one bicolor led Status/Error indicator   |
| <b>Communication Protocol</b>  |  |
| Data Link Layer  | POWERLINK use Standard Ethernet Frames:<br>ISO/IEC 8802-3 + IEC 61784-2  |
| Comm. Profile  | EPSP DS 301 v1.2   |
| Device Profile   | CANopen over Ethernet based on DS408 - Fluid Power Technology  |
| Device type  | Slave - supported features:<br>- Ethernet POWERLINK v2.0<br>- Ring Redundancy<br>- Support PollResponse Chaining<br>- Support Multiplexing<br>- Cycle time min 200 µsec<br>- SDO Multiple Parameter Read/Write |
| <b>Startup and configuration (as per EPSP DS301 + EPSP DS 302-A/B/C/D/E)</b> |  |
| Node setting   | E-SW-FIELDBUS and Z-SW-FULL programming software   |
| Baudrate   | 100 Mbit/s (Automatic)   |
| <b>Fieldbus communication diagnostic</b>                                     |  |
| Custom parameters mappable on TPDO for emergency diagnosis                   |  |
| <b>Real-time communication (as per EPSP DS301 + DS408)</b>                   |  |
| RPDO   | 1 PDO message to the driver<br>(max number of of mapping parameters is Device specific)  |
| TPDO   | 1 PDO message from the driver<br>(max number of of mapping parameters is Device specific)  |

|  |
|--|
| <b>Standard references</b>   |
| <i>EPSP DS301</i><br>Ethernet POWERLINK<br>Communication Profile Specification v 1.2   |
| <i>EPSP DS302-A/B/C/D/E</i><br>Ethernet POWERLINK<br>Part A: High Availability v1.1<br>Part B: Multiple ASnd v1.0<br>Part C: PollResponse Chaining v1.0<br>Part D: Multiple PReq/PRes v1.0<br>Part E: Dynamic Node Allocation v1.0   |
| <i>EPSP DS311</i><br>Ethernet POWERLINK<br>XML Device Description v 1.0  |
| <i>CiA DS408</i><br>CANopen – Device Profile for<br>Proportional Hydraulic Valves v 1.5.1  |
| <i>IEC 61076-2-101</i><br>Connectors for electronic equipment<br>- Product Requirements -<br>Part 2-101: Circular connectors<br>- Detail specification for M12 connectors with screw-locking   |
| <i>IEC 61158-2</i><br>Industrial communication networks<br>- Fieldbus specification -<br>Part 2: Physical layer specification and service definition   |
| <i>IEC 61784-2</i><br>Industrial communication networks<br>- Profiles -<br>Part 2: Additional fieldbus profiles for real-time networks based on ISO/IEC 8802-3   |
| <i>IEC 61784-3</i><br>Industrial communication networks<br>- Profiles -<br>Part 3: Functional safety fieldbuses -<br>General rules and profile definitions   |
| <i>IEC 61158-300/400/500/600</i><br>Industrial communication networks<br>- Fieldbus specifications -<br>Part 300: Data Link Layer service definition<br>Part 400: Data Link Layer protocol specification<br>Part 500: Application Layer service definition<br>Part 600: Application Layer protocol specification |
| <i>ISO 15745-1</i><br>Industrial automation systems and integration - Open systems application integration framework -<br>Part 1: Generic reference description  |

**Programming interface**

E-SW-FIELDBUS and Z-SW-FULL software using proper cable/adaptor (see tech table **GS500**) or POWERLINK master device

**Configuration file**

XDD (XML Device Description) enclosed in programming software DVD E-SW-FIELDBUS and Z-SW-FULL

**Manuals**

E-MAN-S-EW and STARTUP-FIELDBUS, enclosed in programming software DVD E-SW-FIELDBUS  
Z-MAN-S-EW and STARTUP-FULL, enclosed in programming software DVD Z-SW-FULL

**5 EtherNet/IP features for digital drivers and controllers in EI execution**

**Physical**

|                   |  |
|-------------------|--|
| Ethernet Standard | ISO/IEC 8802-3 frame format  |
| EtherType         | IEEE 802.3   |
| Transmission rate | 10/100 Mbit Full/Half-Duplex   |
| Integrated        | 2-port switch  |
| Cable length      | max 100m   |
| Cable type        | CAT5 (4 wire twisted pair) according with T568B  |
| Network topology  | Device Level Ring (DLR), linear, star structure  |
| Ethernet port     | Led indicator:<br>- two led for Link/Activity indicator (on each port)<br>- one bicolor led Status/Error indicator |

**Communication Protocol**

ODVA CIP Object Model  
 ODVA CIP Object library for Generic Device Profile

- Identity Object (0X01)
- Message Router Object (0x02)
- Assembly Object (0x04)
- Connection Manager Object (0x06)
- Parameter Object (0x0F)
- DLR Object (0x47)
- QoS Object (0x48h)
- Port Object (0xF4)
- TCP/IP Object (0xF5)
- Ethernet Link Object (0xF6)

Valve parameters accessible via Vendor Specific Object 0xA2  
 IP address setting (range 0.0.0.0 - 255.255.255.255):

- TCP/IP Object (0xF5)
- DHCP
- Auxiliary USB communication + Atos Software

I/O Adapter and Explicit Message Server device type  
 Cyclic data transmission via Implicit Messages (transport class 1)

- Minimum RPI for Implicit Messages 1ms
- Total number of supported class 1 connections: 4
- Up to 5 parameters and 20 bytes for each connection
- Trigger types: Cyclic CoS

Acyclic data transmission via Connected and Unconnected Explicit Messages (transport class 3)

- Minimum RPI for Explicit Messages 100ms
- No. of simultaneous Class 3 connections: 6

IT functions (FTP server, web server)

**Standard references**

**IEC 61918**  
 Industrial communication networks  
 - Installation of communication networks in industrial premises

**IEC 61076-2-101**  
 Connectors for electronic equipment  
 - Product Requirements -  
 Part 2-101: Circular connectors  
 - Detail specification for M12 connectors with screw-locking

**EC 61158-1**  
 Industrial communication networks  
 - Fieldbus specification -  
 Part 1: Overview and guidance for the IEC 61158 and IEC 61784 series

**IEC 61158-2**  
 Industrial communication networks  
 - Fieldbus specification -  
 Part 2: Physical layer specification and service definition

**IEC 61784-1**  
 Industrial communication networks  
 - Profiles -  
 Part 1: Fieldbus profile

**IEC 61784-2**  
 Industrial communication networks  
 - Profiles -  
 Part 2: Additional fieldbus profiles for real-time networks based on ISO/IEC 8802-3

**IEC 61784-3**  
 Industrial communication networks  
 - Profiles -  
 Part 3: Functional safety fieldbuses - General rules and profile definitions

**IEC 61784-5-2**  
 Industrial communication networks  
 - Profiles -  
 Part 5-2: Installation of fieldbuses - Installation profiles for CPF 2

**ISO 15745-4**  
 Industrial automation systems and integration - Open systems application integration framework -  
 Part 4: Reference description for Ethernet-based control systems

**Programming interface**

E-SW-FIELDBUS and Z-SW-FULL software using proper cable/adaptor (see tech table **GS500**) or EtherNet/IP scanner device

**Configuration file**

EDS (Electronic Data Sheet) enclosed in programming software DVD E-SW-FIELDBUS and Z-SW-FULL

**Manuals**

E-MAN-S-EI and STARTUP-FIELDBUS, enclosed in programming software DVD E-SW-FIELDBUS  
 Z-MAN-S-EI and STARTUP-FULL, enclosed in programming software DVD Z-SW-FULL